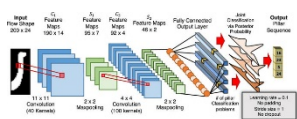
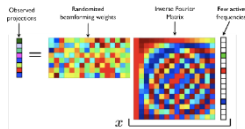


Machine Learning for CS MRI: From Model-Based Methods to Deep Learning

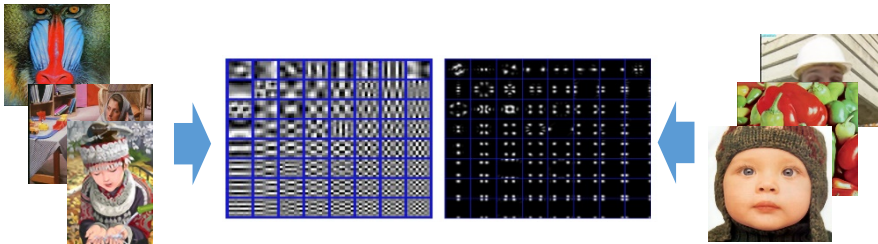
Bihan Wen

Nanyang Assistant Professor

School of Electrical and Electronic Engineering (EEE)
Nanyang Technological University (NTU)

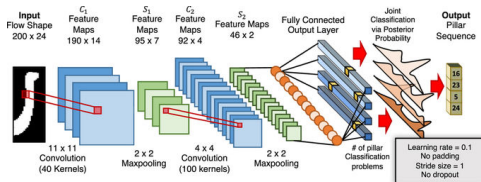
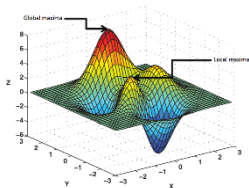


- Artificial Intelligence (AI): Data-Driven Models



Data-Driven Models > Analytical Models

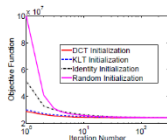
- Artificial Intelligence (AI): Data-Driven Models
- Machine Learning



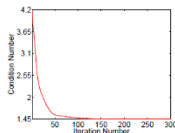
Deep Learning, Optimization, Sparse Coding, etc.

About me

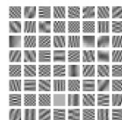
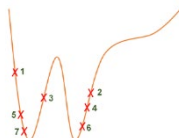
- Artificial Intelligence (AI): Data-Driven Models
- Machine Learning
- Solutions with Mathematical Analysis



Objective Function



$\kappa(W)$ - Random Init



Learnt W - Random Init

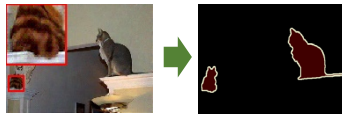
Mathematical Analysis, Convergence Guarantee, etc.

About me

- Artificial Intelligence (AI): Data-Driven Models
- Machine Learning
- Solutions with Mathematical Analysis
- Applications with State-of-the-art Results



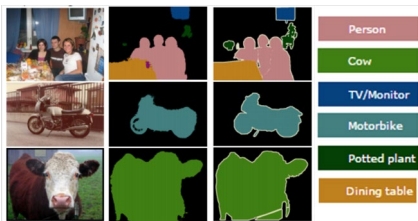
Restoration



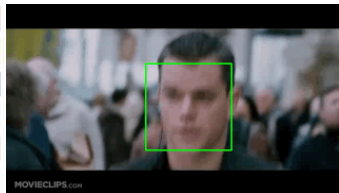
Analysis

Computer Vision vs. Image Reconstruction

Computer Vision



- Image Analysis

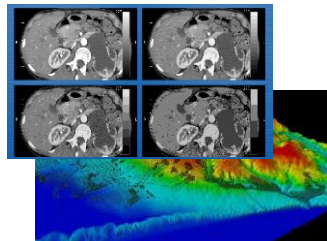


- Video Analysis

Image Reconstruction



- Image Restoration



- Computational Imaging

Computer Vision vs. Image Formation

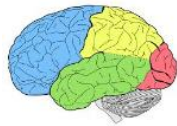
Computer Vision



“Cat”



Classification
+ Localization



understanding

Image Reconstruction



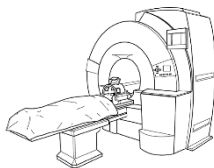
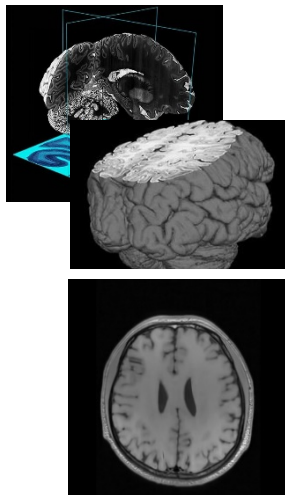
90	91	92	93	94	95	96	97	98	99
80	81	82	83	84	85	86	87	88	89
70	71	72	73	74	75	76	77	78	79
60	61	62	63	64	65	66	67	68	69
50	51	52	53	54	55	56	57	58	59
40	41	42	43	44	45	46	47	48	49
30	31	32	33	34	35	36	37	38	39
20	21	22	23	24	25	26	27	28	29
10	11	12	13	14	15	16	17	18	19
0	1	2	3	4	5	6	7	8	9



Sensing

- Compressed Sensing MRI
- Why Do We Need Data Models?
- Tutorial on Transform Learning (TL) for MRI
- From Model-Based Method to Deep Learning

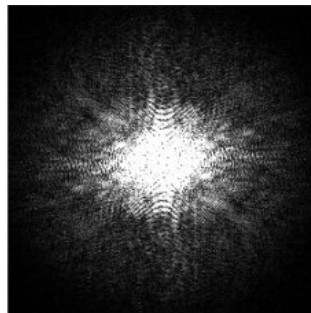
Magnetic Resonance Imaging (MRI)



MR sampling



**MR image
reconstruction**



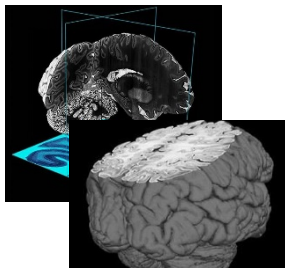
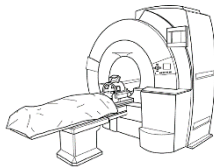


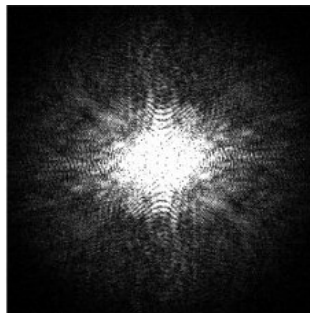
Image Space



MR sampling



MR image
reconstruction



K-Space

Why MRI?

- Non-invasive



Why MRI?

- Non-invasive
- Non-ionizing



Why MRI?

- Non-invasive
- Non-ionizing
- Variety of Contrast and Visualization



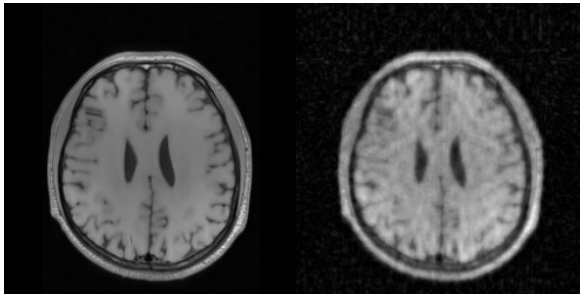
Why Compressed Sensing (CS)?

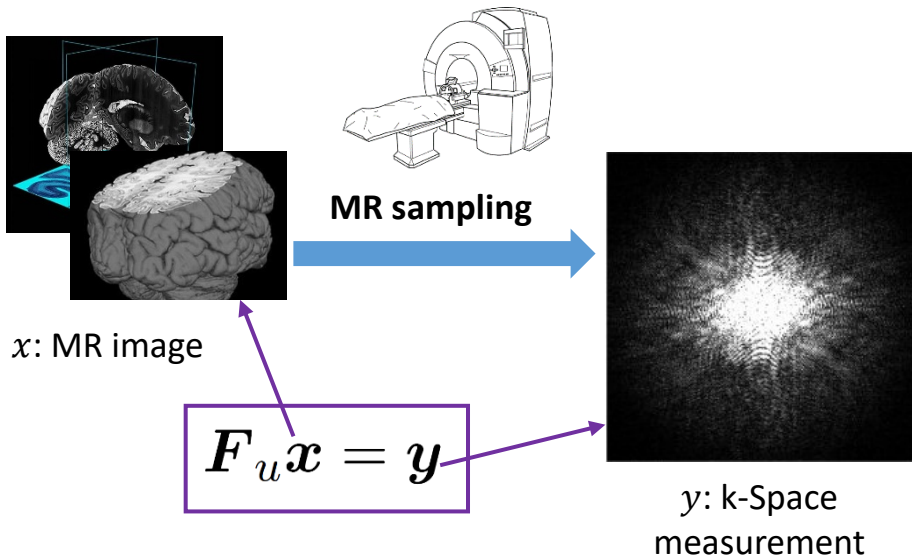
- **Scan time is too long**

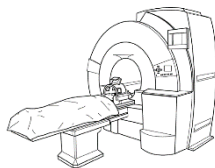
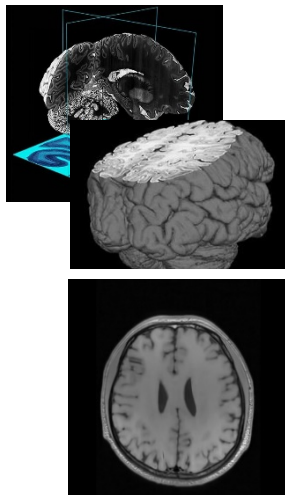


Why Compressed Sensing (CS)?

- **Scan time is too long**
- **Image Resolution**



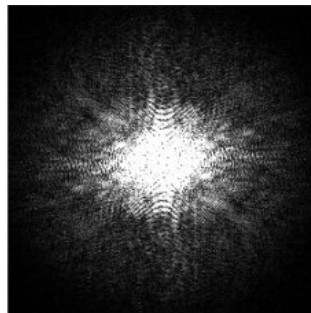


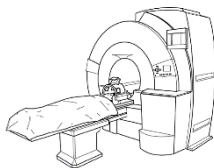
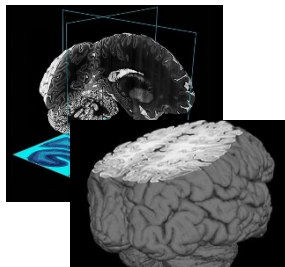


MR sampling



**MR image
reconstruction**

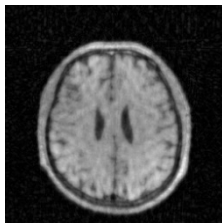




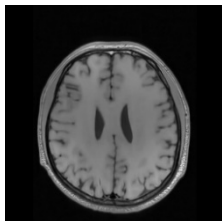
under-sampling



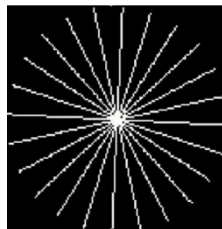
**Naïve
Reconstruction**



**CS: better reconstruction
via image modeling**



**Compressed
Sensing MRI**



Transform-
domain
Sparsity

$$\hat{x} = \underset{x}{\operatorname{argmin}} \quad \boxed{\|\Psi x\|_0} \quad \text{s.t.} \quad F_u x = y$$



$$\hat{x} = \underset{x}{\operatorname{argmin}} \quad \boxed{\|\Psi x\|_0} + v \|F_u x - y\|_2^2$$



Sparsity as the regularizer

Why do we need Data Model?



What makes images look like images?

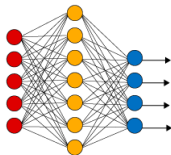
How to distinguish desired pattern from others?

Why do we need Data Model?

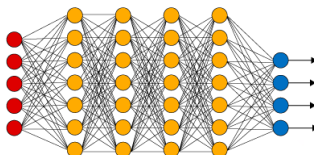
Data Models

Why do we need Data Model?

Simple Neural Network



Deep Learning Neural Network

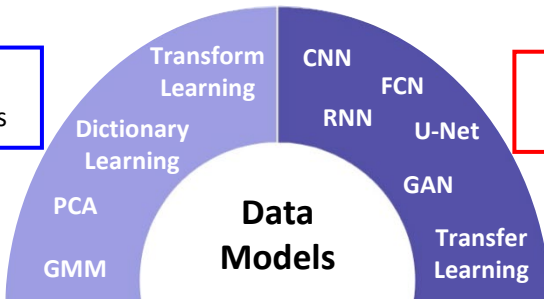


● Input Layer

● Hidden Layer

● Output Layer

Shallow
Methods



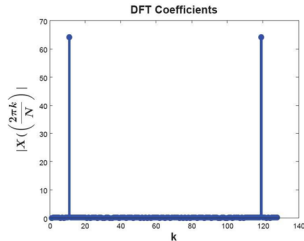
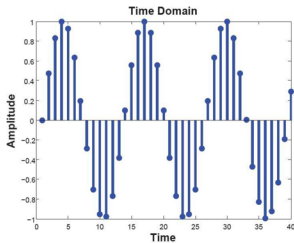
Deep
Methods

Machine Learning

Sparsity

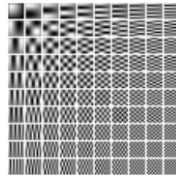
- A vector $x \in \mathbb{R}^n$ is **sparse** \Leftrightarrow Most of its coefficients are equal to zero.
- **Define:** $\|x\|_0$ = number of non-zero coefficients in x .
- Dense signal may be sparse in certain transform domain.

- **Example:** $x(n) = \sin\left(\frac{2\pi 10}{128}n\right)$,
 - Sinusoids are sparse in DFT domain.

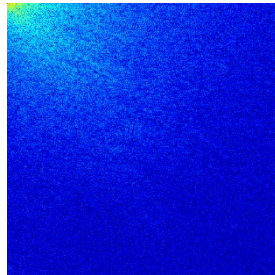




Natural Image



2D Discrete Cosine Transform (2D DCT)

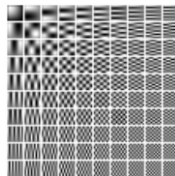


Highly sparse DCT coefficients

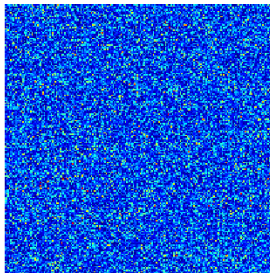
Sparsity



**i.i.d. White
Gaussian Noise**

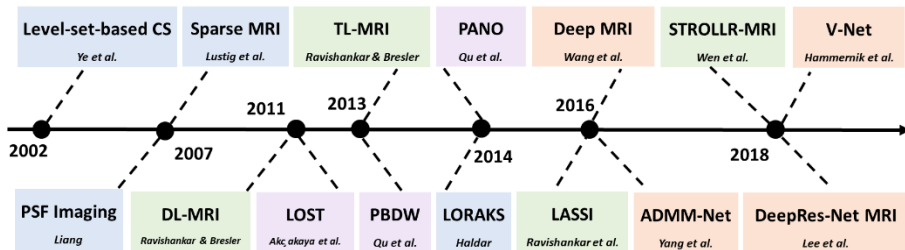


**2D Discrete Cosine
Transform (2D DCT)**



i.i.d. White Gaussian

Sparsity and Beyond



Classic
CS MRI

Semi-Adaptive
CS MRI

Learning-Based
CS MRI

Deep Learning
CS MRI

Methods	Sparse Model				Block Matching	Supervised Learning	Low-Rank Modeling
	Fixed	Directional	DL	TL			
Sparse MRI [5]	✓						
PBDW [19]	✓	✓					
LORAKS [23]							✓
PANO [20]	✓				✓		
DLMRI [6]			✓				
SOUPDIL-MRI [28]			✓				
LASSI [22]			✓				✓
STL-MRI [24]				✓			
FRIST-MRI [27]		✓		✓			
STROLLR-MRI [12]				✓	✓		✓
ADMM-Net [8]						✓	
BCD-Net [9, 33]				✓		✓	

[Wen et al., SPM 2020]

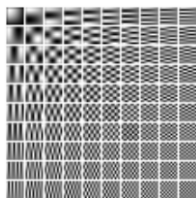
Transform Learning for Better Sparsity

Fixed
Transform

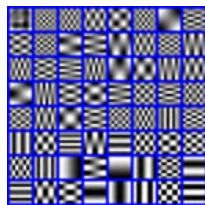
$$\hat{x} = \operatorname{argmin}_x \|\Psi x\|_0 + v \|F_u x - y\|_2^2$$

$$\hat{x} = \operatorname{argmin}_x \|F_u x - y\|_2^2 + \mathfrak{R}_{TL}(x)$$

Transform-Learning (TL) based regularizer



2D DCT

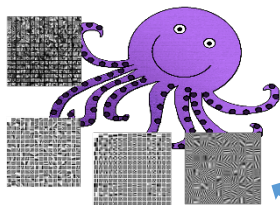


Learned Transform

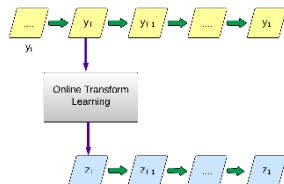
$$\mathfrak{R}_{TL}(x)$$

1. Sparsifying Transform Learning (STL)
2. Unitary Transform Learning (UT)
3. Learning a UNION of Transforms (UNITE)
4. Flipping and Rotation Invariant Sparsifying Transform (FRIST)
5. Sparsifying TRAnsform Learning and Low-Rankness (STROLLR)

Transform Learning

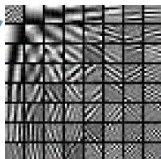


Octobos: Learning a Union of Transforms



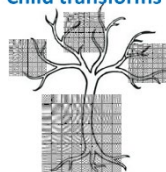
z_i : Learnt Transform/Sparse Codes/Signal Estimates

Online Transform Learning



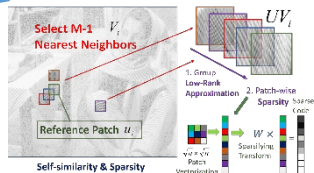
Sparsifying Transform Learning

Child transforms



Parent transform

FRIST: flipping and rotation invariant Transform Learning



STROLLR: Transform Learning with Low-Rank Regularization

1. Sparsifying Transform Learning (STL)

$$\hat{\mathbf{x}} = \underset{\mathbf{x}}{\operatorname{argmin}} \|\mathbf{F}_u \mathbf{x} - \mathbf{y}\|_2^2 + \mathfrak{R}_{TL}(\mathbf{x})$$

$$\mathfrak{R}_{STL}(\mathbf{x}) \triangleq \underset{\mathbf{W}, \{\mathbf{b}_i\}}{\operatorname{argmin}} \sum_{i=1}^N \{\|\mathbf{W} \mathbf{P}_i \mathbf{x} - \mathbf{b}_i\|_2^2 + \tau^2 \|\mathbf{b}_i\|_0\} + \frac{\lambda}{2} \|\mathbf{W}\|_F^2 - \lambda \log(\det \mathbf{W})$$

Well-conditioning Regularizer for \mathbf{W}

1. Coefficient λ controls the condition number
2. Prevents trivial solution, i.e., $\mathbf{W} = 0$

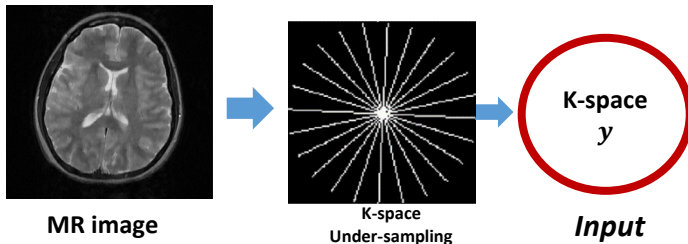
2. Unitary Transform Learning (UT)

$$\hat{\mathbf{x}} = \underset{\mathbf{x}}{\operatorname{argmin}} \|\mathbf{F}_u \mathbf{x} - \mathbf{y}\|_2^2 + \mathfrak{R}_{TL}(\mathbf{x})$$

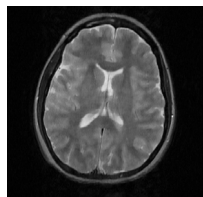
$$\mathfrak{R}_{UT}(\mathbf{x}) \triangleq \underset{\mathbf{W}, \{\mathbf{b}_i\}}{\operatorname{argmin}} \sum_{i=1}^N \{\|\mathbf{W} \mathbf{P}_i \mathbf{x} - \mathbf{b}_i\|_2^2 + \tau^2 \|\mathbf{b}_i\|_0\} \quad \text{s.t.} \quad \mathbf{W}^H \mathbf{W} = \mathbf{I}_n$$

1. When $\lambda \rightarrow \infty$, it is equivalent to unitary condition.
2. Wavelets, DCT, Discrete Fourier Transforms are all unitary.
3. Closed-form solution

Sensing and Reconstruction



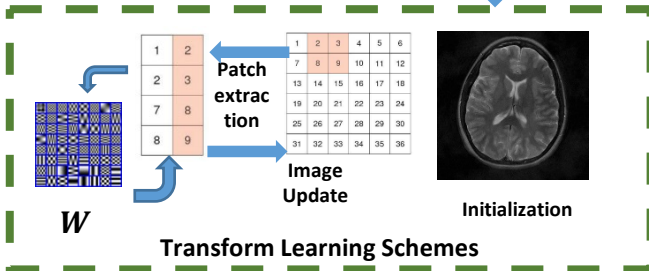
Output x



Reconstructed

\hat{x}

[Wen et al., SPM 2020]



3. Learning a UNION of Transforms (UNITE)

$$\hat{\mathbf{x}} = \operatorname{argmin}_{\mathbf{x}} \|\mathbf{F}_u \mathbf{x} - \mathbf{y}\|_2^2 + \mathfrak{R}_{TL}(\mathbf{x})$$

$$\mathfrak{R}_{UNITE}(\mathbf{x}) \triangleq \operatorname{argmin}_{\{\mathbf{b}_i\}, \{\mathbf{W}_k, C_k\}} \sum_{k=1}^K \sum_{i \in C_k} \{\|\mathbf{W}_k \mathbf{P}_i \mathbf{x} - \mathbf{b}_i\|_2^2 + \tau^2 \|\mathbf{b}_i\|_0\}$$

$$\text{s.t. } \mathbf{W}_k^H \mathbf{W}_k = \mathbf{I}_n, \quad \{C_k\} \in G \quad \forall k.$$

1. A union of transforms $\{\mathbf{W}_k\}$ with the membership $\{C_k\}$.
2. Patches with similar textures will be grouped together.

4. Flipping and Rotation Invariant Sparsifying Transform (FRIST)

$$\hat{\mathbf{x}} = \underset{\mathbf{x}}{\operatorname{argmin}} \|\mathbf{F}_u \mathbf{x} - \mathbf{y}\|_2^2 + \mathfrak{R}_{TL}(\mathbf{x})$$

$$\mathfrak{R}_{FRIST}(\mathbf{x}) \triangleq \underset{\mathbf{W}, \{\mathbf{b}_i\}, \{C_k\}}{\operatorname{argmin}} \sum_{k=1}^K \sum_{i \in C_k} \{\|\mathbf{W} \Phi_k \mathbf{P}_i \mathbf{x} - \mathbf{b}_i\|_2^2 + \tau^2 \|\mathbf{b}_i\|_0\}$$

$$\text{s.t. } \mathbf{W}^H \mathbf{W} = \mathbf{I}_n, \{C_k\} \in G \quad \forall k,$$

1. Pre-defined operators $\{\Phi_k\}$; One parent transform \mathbf{W} .
2. Prevent overfitting; handles rotation and flipping.

5. Sparsifying TRansfOrm Learning and Low-Rankness (STROLLR)

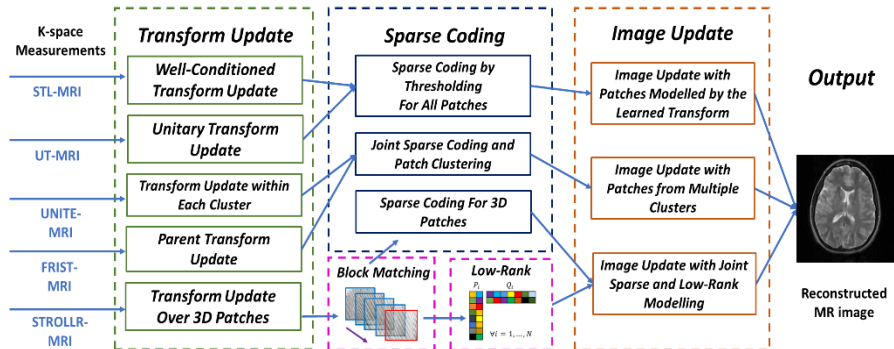
$$\hat{\mathbf{x}} = \underset{\mathbf{x}}{\operatorname{argmin}} \|\mathbf{F}_u \mathbf{x} - \mathbf{y}\|_2^2 + \mathfrak{R}_{TL}(\mathbf{x})$$

$$\mathfrak{R}_{TL}(\mathbf{x}) = \mathfrak{R}_{STROLLR}(\mathbf{x}) \triangleq \gamma^{LR} \mathfrak{R}_{LR}(\mathbf{x}) + \gamma^S \mathfrak{R}_S(\mathbf{x})$$

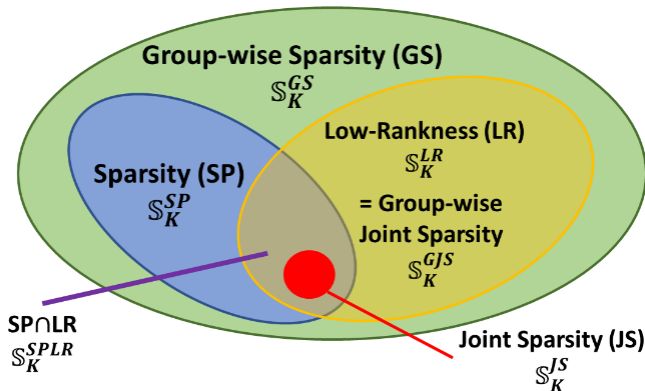
$$\mathfrak{R}_S(\mathbf{x}) = \min_{\{\tilde{\mathbf{b}}_i\}, \mathbf{W}} \sum_{i=1}^N \left\{ \left\| \mathbf{W} \mathbf{C}_i \mathbf{x} - \tilde{\mathbf{b}}_i \right\|_2^2 + \tau^2 \left\| \tilde{\mathbf{b}} \right\|_0 \right\} \quad \text{s.t. } \mathbf{W}^H \mathbf{W} = \mathbf{I}_{nl} \quad \text{Transform Learning}$$

$$\mathfrak{R}_{LR}(\mathbf{x}) = \min_{\{\mathbf{D}_i\}} \sum_{i=1}^N \left\{ \left\| \mathbf{V}_i \mathbf{x} - \mathbf{D}_i \right\|_F^2 + \theta^2 \operatorname{rank}(\mathbf{D}_i) \right\} \quad \text{Low-Rank Modelling}$$

A unified framework for TL-based MRI



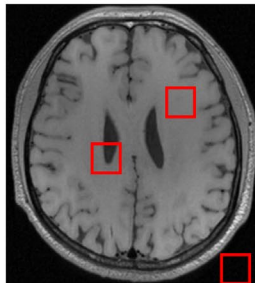
Can you combine any priors, and always gain?



Combine only the complementary priors / image models

Why Compressed Sensing (CS)?

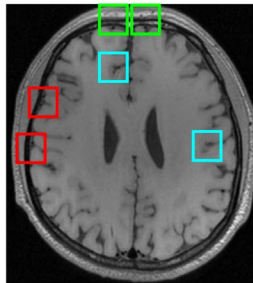
STL-MRI or UTL-MRI



— Local sparsifiable / smooth patches

(a)

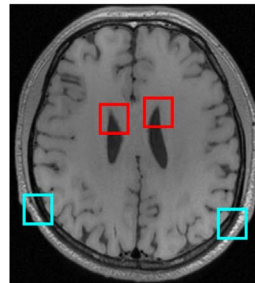
UNITE-MRI or STROLLR-MRI



— Groups of non-Local patches
which contain similar structures

(b)

FRIST-MRI



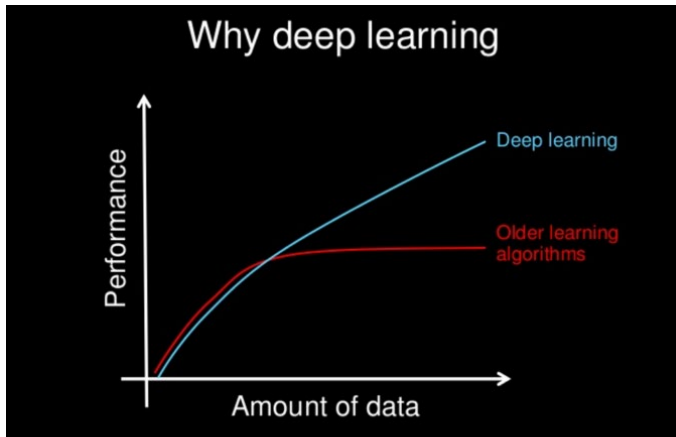
— Similar patches subject to flipping
— Similar patches subject to rotation

(c)

Combine only the complimentary priors / image models

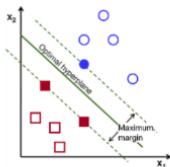
[Wen et al., SPM 2020]

Deep Learning



Representation Learning

Deep Learning



○ SVM

○ GMM

○ Boosting

○ Perceptron

○ Decision Tree

○ PCA

○ Sparse Coding

○ Wavelets

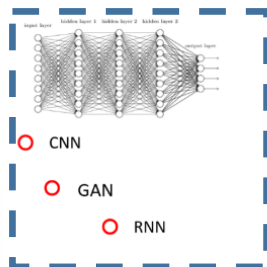
○ Low-Rankness

● Transform Learning

○ Dictionary Learning

$$\begin{bmatrix} \text{color} \\ \text{shape} \\ \text{size} \end{bmatrix} = \begin{bmatrix} \text{color} & \text{shape} & \text{size} & \dots \end{bmatrix} \begin{bmatrix} \text{feature} \\ \text{feature} \\ \text{feature} \end{bmatrix}$$

$y \in \mathbb{R}^m$ $A \in \mathbb{R}^{m \times n}$ $x \in \mathbb{R}^n$



○ CNN

○ GAN

○ RNN

Deep Learning

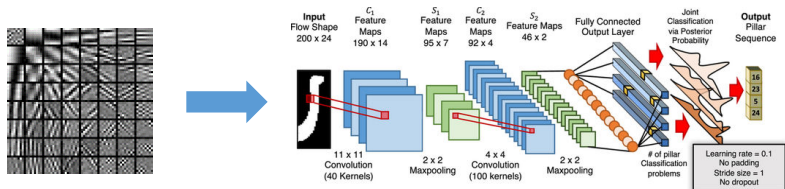
1990

2000

2010

time

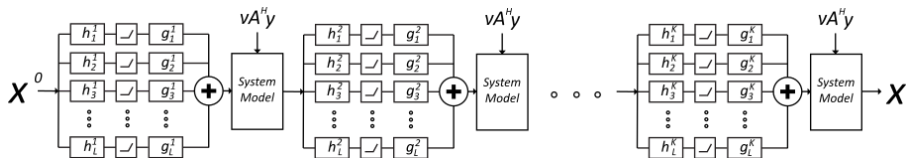
Connection to Unrolled Neural Networks



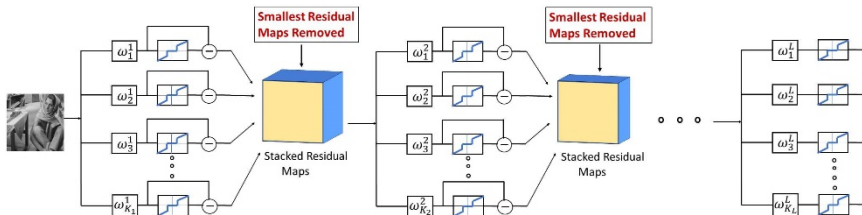
1. Improved Performance
2. Robust to Corruptions

Unrolled Transform Learning for MRI

- Unrolled TL-MRI

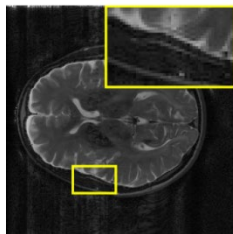


- Multi-Layer Transform Residual Learning

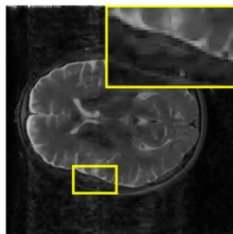


[Ravishankar et al., ISBI 2018]

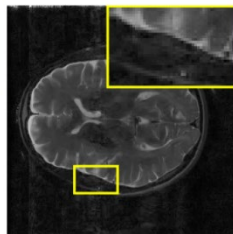
Some Results



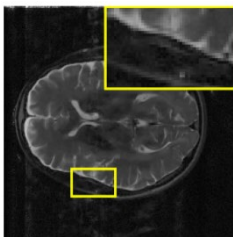
Ground Truth
Example A



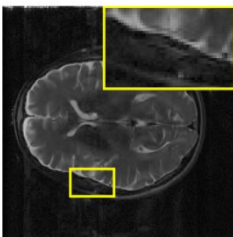
Sparse MRI
(39.07 dB)



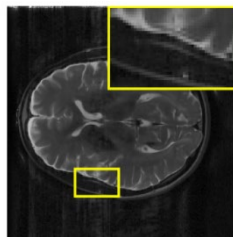
PANO
(41.61 dB)



DL-MRI
(41.73 dB)

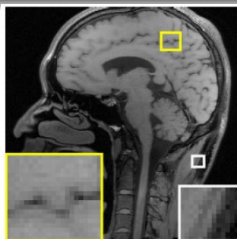


STL-MRI
(41.95 dB)

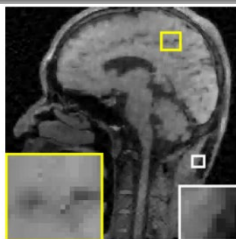


STROLLR-MRI
(43.27 dB)

Some Results



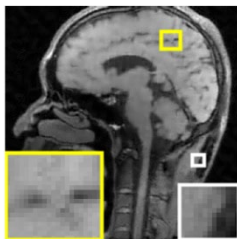
Ground Truth
Example *B*



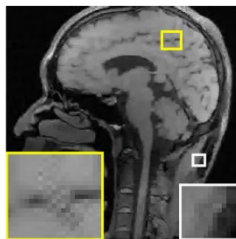
Sparse MRI
(28.03 dB)



PANO
(30.03 dB)



DL-MRI
(29.74 dB)



ADMM-Net
(30.67 dB)



STROLLR-MRI
(32.46 dB)

Conventional

- **Shallow Model**
 - Equivalently one free layer

Deep Learning

- **Deep Model**
 - Multiple free layers



Conventional

- **Shallow Model**
 - One free layer
- **Unsupervised**
 - No training corpus needed
 - Data efficient

Deep Learning

- **Deep Model**
 - Multiple free layers
- **Supervised**
 - Training corpus needed
 - Data inefficient



Conventional

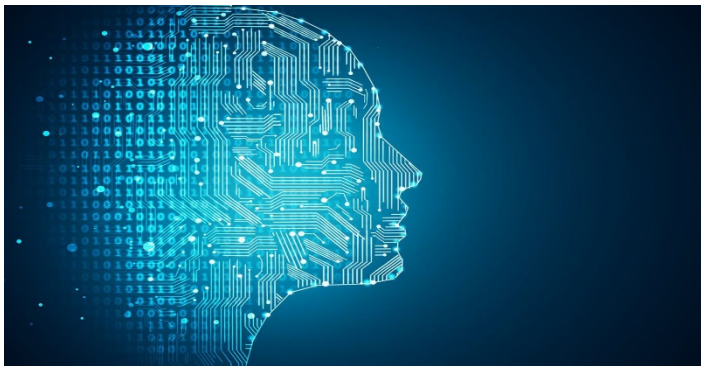
- **Shallow Model**
 - One free layer
- **Unsupervised**
 - No training corpus needed
 - Data efficient
- **Prior-based**
 - Assumption & Understanding of the Data
 - Regularizer & structures of the Model

Deep Learning

- **Deep Model**
 - Multiple free layers
- **Supervised**
 - Training corpus needed
 - Data inefficient
- **Generic**
 - Little assumption
 - Almost free model



Thank you! Questions??



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