



Tian Seng Ng

Flight Systems and Control

A Practical Approach

Series: Springer Aerospace Technology

- Highlights flight structures and their control systems
- Includes Matrix Laboratory (MATLAB) codes/plots and the Virtual Reality Modeling Language (VRML) program as examples
- Provides an introduction to various unmanned aerial vehicle (UAV) systems and their accessories

This book focuses on flight vehicles and their navigational systems, discussing different forms of flight structures and their control systems, from fixed wings to rotary crafts. Software simulation enables testing of the hardware without actual implementation, and the flight simulators, mechanics, glider development and navigation systems presented here are suitable for lab-based experimentation studies. It explores laboratory testing of flight navigational sensors, such as the magnetic, acceleration and Global Positioning System (GPS) units, and illustrates the six-axis inertial measurement unit (IMU) instrumentation as well as its data acquisition methodology. The book offers an introduction to the various unmanned aerial vehicle (UAV) systems and their accessories, including the linear quadratic regulator (LQR) method for controlling the rotorcraft. It also describes a Matrix Laboratory (MATLAB) control algorithm that simulates and runs the lab-based 3 degrees of freedom (DOF) helicopter, as well as LabVIEW software used to validate controller design and data acquisition. Lastly, the book explores future developments in aviation techniques.

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