# Conditional Stein approximation for Itô and Skorohod integrals 

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#### Abstract

We derive conditional Edgeworth-type expansions for Skorohod and Itô integrals with respect to Brownian motion, based on cumulant operators defined by the Malliavin calculus. As a consequence we obtain conditional Stein approximation bounds for multiple stochastic integrals and quadratic Brownian functionals.


Key words: Stein method; Malliavin calculus; Edgeworth expansions; stochastic integral; conditioning; quadratic Brownian functionals.
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## 1 Introduction

Let $\left(B_{t}\right)_{t \in[0, T]}$ be a $d$-dimensional Brownian motion generating the filtration $\left(\mathcal{F}_{t}\right)_{t \in[0, T]}$ on the Wiener space $\Omega$. It has been shown in Theorem 2.1 of [4], that given $B_{T}$, the stochastic integral $\int_{0}^{T} A B_{s} d B_{s}$ is Gaussian $\mathcal{N}\left(0, \int_{0}^{T}\left|A B_{s}\right|^{2} d s\right)$-distributed given $\int_{0}^{T}\left|A B_{s}\right|^{2} d s$ when the $d \times d$ matrix $A$ is skew-symmetrix, as an extension of results of [14] in the case of Lévy's stochastic area with $A=\left(\begin{array}{cc}0 & 1 \\ -1 & 0\end{array}\right)$. On the other hand, it
has recently been shown in [12] that the distribution of $\int_{0}^{T} A B_{s} d B_{s}$ given $\int_{0}^{T}\left|A B_{s}\right|^{2} d s$ is also Gaussian $\mathcal{N}\left(0, \int_{0}^{T}\left|A B_{s}\right|^{2} d s\right)$ when $A$ is a 2-nilpotent $d \times d$ matrix, in connection with results of [13] showing that the filtration $\left(\mathcal{F}_{t}^{k}\right)_{t \in[0, T]}$ of $t \mapsto \int_{0}^{t} A B_{s} d B_{s}$ is generated by $k$ independent Brownian motions, where $k$ is the number of distinct eigenvalues of $A^{\top} A$.

More generally, this type of result has been shown to hold in [12] for stochastic integrals of the form $\int_{0}^{T} u_{t} d B_{t}$ where $\left(u_{t}\right)_{t \in[0, T]}$ is an $\left(\mathcal{F}_{t}\right)$-adapted process, under conditions formulated in terms of the Malliavin calculus, based on the cumulant-moment formulas of [9], [10]. Namely, sufficient conditions on the process $\left(u_{t}\right)_{t \in[0, T]}$ have been given for $\int_{0}^{T} u_{t} d B_{t}$ to be Gaussian $\mathcal{N}\left(0, \int_{0}^{T}\left|u_{t}\right|^{2} d t\right)$-distributed given $\int_{0}^{T}\left|u_{t}\right|^{2} d t$, cf. Theorem 2 therein.

In this paper, using the Malliavin-Stein method on the Wiener space we derive conditional estimates on the distance between the law of $\int_{0}^{T} u_{t} d B_{t}$ and the Gaussian $\mathcal{N}\left(0, \int_{0}^{T}\left|u_{t}\right|^{2} d t\right)$ distribution given $\int_{0}^{T}\left|u_{t}\right|^{2} d t$. For this, we rely on conditional Edgeworth type expansions for random variables represented as the Itô stochastic integral of $\left(u_{t}\right)_{t \in[0, T]}$ with respect to $\left(B_{t}\right)_{t \in[0, T]}$, extending results of [11] to a conditional setting. This approach relies on properties of the Skorohod integral operator $\delta$, which coincides with the Itô stochastic integral with respect to $d$-dimensional Brownian motion on the square-integrable adapted processes.

Letting $H=L^{2}\left(\mathbb{R}_{+} ; \mathbb{R}^{d}\right)$, we consider the standard Sobolev spaces of real-valued, resp. $H$-valued, functionals $\mathbb{D}_{p, k}$, resp. $\mathbb{D}_{p, k}(H), p, k \geq 1$, for the Malliavin gradient $D$ on the Wiener space, cf. § 1.2 of [7] for definitions. Recall that the Skorohod operator $\delta$ is the adjoint of the gradient $D$ through the duality relation

$$
\begin{equation*}
E[F \delta(v)]=E\left[\langle D F, v\rangle_{H}\right], \quad F \in \mathbb{D}_{2,1}, \quad v \in \mathbb{D}_{2,1}(H) \tag{1.1}
\end{equation*}
$$

and we have the commutation relation

$$
\begin{equation*}
D_{t} \delta(u)=u(t)+\delta\left(D_{t} u\right), \quad t \in \mathbb{R}_{+} \tag{1.2}
\end{equation*}
$$

provided that $u \in \mathbb{D}_{2,1}(H)$ and $D_{t} u \in \mathbb{D}_{2,1}(H)$, dt-a.e., cf. Proposition 1.3.2 of [7]. In the sequel we let $\langle h, h\rangle:=\langle h, h\rangle_{H}$ and $\|h\|:=\|h\|_{H}, h \in H$.

## First order conditional duality and expansion

The duality relation (1.1) shows that we have
$E[F \delta(u) f(\delta(u))]=E\left[F\langle u, u\rangle f^{\prime}(\delta(u))\right]+E[\langle u, D F\rangle f(\delta(u))]+E\left[F f^{\prime}(\delta(u))\langle u, \delta(D u)\rangle\right]$, for $f \in \mathcal{C}_{b}^{1}(\mathbb{R})$, provided that $u \in \mathbb{D}_{2,2}(H)$. Applying this relation to $F=g(\langle u, u\rangle)$ where $g:(0, \infty) \rightarrow(0, \infty)$ is in $\mathcal{C}_{b}^{1}((0, \infty))$, under the condition $\langle u,(D u) u\rangle=0$ we have

$$
\begin{aligned}
& E[F \delta(u) f(\delta(u))] \\
& =E\left[F\langle u, u\rangle f^{\prime}(\delta(u))\right]+E\left[\langle u, D\langle u, u\rangle\rangle f(\delta(u)) g^{\prime}(\langle u, u\rangle)\right]+E\left[F f^{\prime}(\delta(u))\langle u, \delta(D u)\rangle\right] \\
& \left.=E\left[F\langle u, u\rangle f^{\prime}(\delta(u))\right]+2 E[\langle u,(D u) u\rangle\rangle f(\delta(u)) g^{\prime}(\langle u, u\rangle)\right]+E\left[F\langle u, \delta(D u)\rangle f^{\prime}(\delta(u))\right] \\
& =E\left[F\langle u, u\rangle f^{\prime}(\delta(u))\right]+E\left[F\langle u, \delta(D u)\rangle f^{\prime}(\delta(u))\right],
\end{aligned}
$$

which yields

$$
\begin{equation*}
E_{\mid u[ }\left[\delta(u) f(\delta(u))-\langle u, u\rangle f^{\prime}(\delta(u))\right]=E_{|u|}\left[\langle u, \delta(D u)\rangle f^{\prime}(\delta(u))\right], \tag{1.3}
\end{equation*}
$$

for $u \in \mathbb{D}_{2,1}(H), F \in \mathbb{D}_{2,1}$ and $f \in \mathcal{C}_{b}^{1}(\mathbb{R})$, where

$$
E_{|u|}[F]:=E[F \mid\langle u, u\rangle]
$$

denotes the conditional expectation given $\langle u, u\rangle$.

Let now $\mathcal{N}(0, g(\|u\|))$ denote a centered Gaussian random variable with variance $g(\|u\|)$, where $g:(0, \infty) \rightarrow(0, \infty)$ is a measurable function. Applying the above relation (1.3) to the solution $f_{x}$ of the Stein equation

$$
\begin{equation*}
\mathbf{1}_{(-\infty, x]}(z)-\Phi_{g(\|u\|)}(x)=g(\|u\|) f_{x}^{\prime}(z)-z f_{x}(z), \quad z \in \mathbb{R} \tag{1.4}
\end{equation*}
$$

satisfying the bounds $\left\|f_{x}\right\|_{\infty} \leq \sqrt{2 \pi} / 4$ and $\left\|f_{x}^{\prime}\right\|_{\infty} \leq 1 / \sqrt{g(\|u\|)}$, cf. Lemma 2.2-(v) of [3], yields the conditional expansion
$P(\delta(u) \leq x \mid\|u\|)=\Phi_{g(\|u\|)}(x)+E_{|u|}\left[(g(\|u\|)-\langle u, u\rangle) f_{x}^{\prime}(\delta(u))\right]-E\left[\langle u, \delta(D u)\rangle f_{x}^{\prime}(\delta(u))\right]$,
$x \in \mathbb{R}$, around the Gaussian cumulative distribution function $\Phi_{g(\|u\|)}(x)$, with $u \in$ $\mathbb{D}_{2,1}(H)$.

In Section 2 we will expand this approach to Edgeworth type expansion of all orders, based on a family of cumulant operators that are associated to the process $\left(u_{t}\right)_{t \in[0, T]}$. We refer to [1], [5], [2] for other approaches to Edgeworth expansions via the Stein method and the Malliavin calculus.

In Section 3, we derive conditional Stein approximation bounds for the distance between $\delta(u)$ and the Gaussian distribution with variance $g(\|u\|)$ Section 4 treats the case of double stochastic integrals, which includes the quadratic functional $\int_{0}^{T} A B_{s} d B_{s}$ as a particular case.

## 2 Conditional Edgeworth type expansions

Given $u \in \mathbb{D}_{2,1}(H)$ and $k \geq 1$, we define the operator composition $(D u)^{k}$ in the sense of matrix powers with continuous indices, namely, $(D u)^{k}$ denotes the random operator on $H$ almost surely defined by

$$
\begin{equation*}
(D u)^{k} h_{s}=\int_{0}^{\infty} \cdots \int_{0}^{\infty}\left(D_{t_{k}} u_{s} D_{t_{k-1}} u_{t_{k}} \cdots D_{t_{1}} u_{t_{2}}\right) h_{t_{1}} d t_{1} \cdots d t_{k}, \quad s \in \mathbb{R}_{+}, \quad h \in H \tag{2.1}
\end{equation*}
$$

cf. e.g. $\S 7$ of [10], [9], [8] for details. The adjoint $D^{*} u$ of $D u$ on $H$ satisfies

$$
\langle(D u) v, h\rangle=\left\langle v,\left(D^{*} u\right) h\right\rangle, \quad h, v \in H,
$$

with $\langle\cdot, \cdot\rangle=\langle\cdot, \cdot\rangle_{H}$, and is given by

$$
\left(D^{*} u\right) v_{s}=\int_{0}^{\infty}\left(D_{s} u_{t}\right) v_{t} d t, \quad s \in \mathbb{R}_{+}, \quad v \in L^{2}(W ; H)
$$

The next proposition reformulates Proposition 2.1 of [11] in a conditional setting given the random value of $\langle u, u\rangle$, whereas the case where $\langle u, u\rangle$ is deterministic (random isometries) has been treated in [11] based on the relation $\left\langle u,(D u)^{k} u\right\rangle=$ $\left\langle(D u)^{k-1} u, D\langle u, u\rangle\right\rangle / 2, u \in \mathbb{D}_{k+2,1}(H), k \geq 1$.

Proposition 2.1 Let $n \geq 1$ and assume that $u \in \mathbb{D}_{k, 2}(H)$ for all $k=1, \ldots, n+2$ and $\left\langle u,(D u)^{k} u\right\rangle=0$ for $k=1, \ldots, n+1$. Then for all $f \in \mathcal{C}_{b}^{n+1}(\mathbb{R})$ we have

$$
\begin{align*}
& E_{|u|}[\delta(u) f(\delta(u))]=E_{|u|}\left[\left(\langle u, u\rangle+\operatorname{trace}(D u)^{2}\right) f^{\prime}(\delta(u))\right]  \tag{2.2}\\
& \quad+\sum_{k=2}^{n} E_{|u|}\left[\left\langle D^{*} u, D\left((D u)^{k-1} u\right)\right\rangle f^{(k)}(\delta(u))\right]+E_{|u|}\left[\left\langle(D u)^{n} u, \delta(D u)\right\rangle f^{(n+1)}(\delta(u))\right] .
\end{align*}
$$

Proof. From Proposition 2.1 of [11] we have

$$
\begin{equation*}
E[F \delta(u) f(\delta(u))]=\sum_{k=0}^{n} E\left[f^{(k)}(\delta(u)) \Gamma_{k+1}^{u} F\right]+E\left[F\left\langle(D u)^{n} u, \delta(D u)\right\rangle f^{(n+1)}(\delta(u))\right] \tag{2.3}
\end{equation*}
$$

where

$$
\Gamma_{k}^{u}: \mathbb{D}_{2,1} \longrightarrow L^{2}(\Omega), \quad k \geq 1
$$

is defined for $u \in \mathbb{D}_{k, 2}(H)$, by $\Gamma_{1}^{u} F:=\langle u, D F\rangle$ and

$$
\Gamma_{k}^{u} F:=F\left\langle(D u)^{k-2} u, u\right\rangle+F\left\langle D^{*} u, D\left((D u)^{k-2} u\right)\right\rangle+\left\langle(D u)^{k-1} u, D F\right\rangle, \quad k \geq 2 .
$$

Next, for F of the form $F=g\left(\int_{0}^{T}\left|u_{t}\right|^{2} d t\right), g \in \mathcal{C}_{b}^{1}(\mathbb{R})$ and $k \geq 1$ we have:

$$
\begin{align*}
& \Gamma_{k}^{u} F \\
&=\left.\mathbf{1}_{\{k=2\}}\langle u, u\rangle g\left(\int_{0}^{T}\left|u_{t}\right|^{2} d t\right)+\left.g^{\prime}\left(\int_{0}^{T}\left|u_{t}\right|^{2} d t\right) \int_{0}^{T}\left\langle D_{t} \int_{0}^{T}\right| u_{s}\right|^{2} d s,(D u)^{k-1} u_{t}\right\rangle_{\mathbb{R}^{d}} d t \\
&+g\left(\int_{0}^{T}\left|u_{t}\right|^{2} d t\right)\left\langle D^{*} u, D\left((D u)^{k-2} u\right)\right\rangle \\
&= \mathbf{1}_{\{k=2\}}\langle u, u\rangle g\left(\int_{0}^{T}\left|u_{t}\right|^{2} d t\right)+2 g^{\prime}\left(\int_{0}^{T}\left|u_{t}\right|^{2} d t\right) \int_{0}^{T}\left\langle u_{s},(D u)^{k} u_{s}\right\rangle_{\mathbb{R}^{d}} d s \\
&+\mathbf{1}_{\{k \geq 2\}} g\left(\int_{0}^{T}\left|u_{t}\right|^{2} d t\right)\left\langle D^{*} u, D\left((D u)^{k-2} u\right)\right\rangle \\
&= \mathbf{1}_{\{k=2\}}\langle u, u\rangle F+\mathbf{1}_{\{k \geq 2\}}\left\langle D^{*} u, D\left((D u)^{k-2} u\right)\right\rangle F . \tag{2.4}
\end{align*}
$$

Hence from (2.3) we find

$$
\begin{aligned}
& E[F \delta(u) f(\delta(u))]=E\left[F\left(\langle u, u\rangle+\operatorname{trace}(D u)^{2}\right) f^{\prime}(\delta(u))\right] \\
& \quad+\sum_{k=2}^{n} E\left[F\left\langle D^{*} u, D\left((D u)^{k-1} u\right)\right\rangle f^{(k)}(\delta(u))\right]+E\left[F\left\langle(D u)^{n} u, \delta(D u)\right\rangle f^{(n+1)}(\delta(u))\right],
\end{aligned}
$$

where we used the relation

$$
\begin{equation*}
\Gamma_{2}^{u} \mathbf{1}=\langle u, u\rangle+\left\langle D^{*} u, D u\right\rangle_{H \otimes H}=\langle u, u\rangle+\operatorname{trace}(D u)^{2} . \tag{2.5}
\end{equation*}
$$

Proposition 2.1 also covers the following particular settings.
(i) Quasi-nilpotent processes. Given $n \geq 0$, when trace $(D u)^{k}=0$ for all $k=$ $2, \ldots, n+1$, under the conditions of Proposition 2.1 we have

$$
E_{|u|}[\delta(u) f(\delta(u))]=\langle u, u\rangle E_{|u|}\left[f^{\prime}(\delta(u))\right]+E_{|u|}\left[f^{(n+1)}(\delta(u))\left\langle(D u)^{n} u, \delta(D u)\right\rangle\right] .
$$

When trace $(D u)^{k}=0$ for all $k \geq 2$, this recovers the conditional Gaussian integration by parts formula

$$
E_{|u|}[\delta(u) f(\delta(u))]=\langle u, u\rangle E_{|u|}\left[f^{\prime}(\delta(u))\right],
$$

showing that $\delta(u)$ has the distribution $\mathcal{N}\left(0, \int_{0}^{T}\left|u_{t}\right|^{2} d t\right)$ given $\int_{0}^{T}\left|u_{t}\right|^{2} d t$. This setting includes the particular cases where $\left(u_{t}\right)_{t \in \mathbb{R}_{+}}$is an $\left(\mathcal{F}_{t}\right)_{t \in \mathbb{R}_{+}}$-adapted process, cf. e.g. Lemma 3.5 of [8] and references therein, in which case $\delta(u)$ coincides with the Itô integral of $u$, cf. Proposition 1.3.11 of [7].
(ii) Multiple stochastic integrals. Taking $u_{t}:=I_{m-1}\left(f_{m}(*, t)\right)$, where $m \geq 1$ and $f_{m}$ is a symmetric square-integrable function on $\mathbb{R}_{+}^{m}$, we have $\delta(u)=I_{m}\left(f_{m}\right)$ and

$$
\begin{equation*}
\delta\left(D_{t} u\right)=(m-1) I_{m-1}\left(f_{m}(*, t)\right)=(m-1) u_{t}, \quad t \in \mathbb{R}_{+} \tag{2.6}
\end{equation*}
$$

Hence, under the conditions of Proposition 2.1 applied to $u_{t}=I_{m-1}\left(f_{m}(*, t)\right)$, we get

$$
\begin{aligned}
& E_{|u|}\left[I_{m}\left(f_{m}\right) f\left(I_{m}\left(f_{m}\right)\right)\right] \\
& \quad=\langle u, u\rangle E_{|u|}\left[f^{\prime}\left(I_{m}\left(f_{m}\right)\right)\right]+\sum_{k=1}^{n} E_{|u|}\left[\left\langle D^{*} u, D\left((D u)^{k-1} u\right)\right\rangle f^{(k)}\left(I_{m}\left(f_{m}\right)\right)\right] .
\end{aligned}
$$

Remark 2.2 By replacing $F$ in Equation (2.4) of the proof of Proposition 2.1 with $F$ of the form

$$
F=g\left(\int_{a_{i}}^{b_{i}}\left|u_{t}\right|^{2} d t, \ldots, \int_{a_{d}}^{b_{d}}\left|u_{t}\right|^{2} d t\right), \quad 0 \leq a_{i} \leq b_{i} \leq T, \quad i=1, \ldots, d,
$$

where $g \in \mathcal{C}_{b}^{1}\left(\mathbb{R}^{d}\right)$, we can rewrite (2.2) by conditioning with respect to $\left(u_{t}\right)_{t \in[0, T]}$, under the stronger condition $\left\langle u_{t},(D u)^{k} u_{t}\right\rangle_{\mathbb{R}^{d}}=0, t \in[0, T], k=1, \ldots, n+1$.

## 3 Conditional Stein approximation

From now on we work with $d=1$ and a one-dimensional Brownian motion $\left(B_{t}\right)_{t \in \mathbb{R}_{+}}$. Given $h: \mathbb{R} \rightarrow \mathbb{R}$ an absolutely continuous function with bounded derivative, the functional equation

$$
\begin{equation*}
h(z)-E_{|u|}\left[h\left(\mathcal{N}_{g(\|u\|)}\right)\right]=g(\|u\|) f^{\prime}(z)-z f(z), \quad z \in \mathbb{R} \tag{3.1}
\end{equation*}
$$

has a solution $f_{h} \in \mathcal{C}_{b}^{1}(\mathbb{R})$ which is twice differentiable and satisfies the bounds

$$
\left\|f_{h}^{\prime}\right\|_{\infty} \leq\left\|h^{\prime}\right\|_{\infty} / \sqrt{g(\|u\|)} \quad \text { and } \quad\left\|f_{h}^{\prime \prime}\right\|_{\infty} \leq 2\left\|h^{\prime}\right\|_{\infty} / g(\|u\|), \quad x \in \mathbb{R}
$$

cf. Lemma 1.2-(v) of [6]. Let

$$
d_{|u|}(F, G)=\sup _{h \in \mathcal{L}}\left|E_{|u|}[h(F)]-E_{|u|}[h(G)]\right|
$$

denote the Wasserstein distance between the conditional laws of $F$ and $G$ given $\|u\|$, where $\mathcal{L}$ denotes the class of 1 -Lipschitz functions.

Proposition 3.1 Let $u \in \bigcap_{k=1}^{3} \mathbb{D}_{k, 2}(H)$, such that $\langle u,(D u) u\rangle=\left\langle u,(D u)^{2} u\right\rangle=0$. We have
$d_{|u|}\left(\delta(u), \mathcal{N}_{g(\|u\|)}\right) \leq \frac{1}{\sqrt{g(\|u\|)}}\left|g(\|u\|)-\operatorname{Var}_{|u|}[\delta(u)]\right|+\frac{2}{g(\|u\|)} E_{|u|}[|\langle(D u) u, \delta(D u)\rangle|]$.

Proof. Applying Proposition 2.1 with $n=1$ shows that
$E_{|u|}[\delta(u) f(\delta(u))]=E_{|u|}\left[\left(\langle u, u\rangle+\operatorname{trace}(D u)^{2}\right) f^{\prime}(\delta(u))\right]+E_{|u|}\left[\langle(D u) u, \delta(D u)\rangle f^{\prime \prime}(\delta(u))\right]$,
hence for any continuous function $h: \mathbb{R} \rightarrow[0,1]$, denoting by $f_{h}$ the solution to (3.1) we have
$\left|E_{|u|}[h(\delta(u))]-E_{|u|}\left[h\left(\mathcal{N}_{g(\|u\|)}\right)\right]\right|$

$$
\begin{aligned}
& =\left|E_{|u|}\left[\delta(u) f_{h}(\delta(u))-g(\|u\|) f_{h}^{\prime}(\delta(u))\right]\right| \\
& =\left|E_{|u|}\left[(\langle u, u\rangle-g(\|u\|)) f_{h}^{\prime}(\delta(u))+\operatorname{trace}(D u)^{2} f_{h}^{\prime}(\delta(u))+\langle(D u) u, \delta(D u)\rangle f_{h}^{\prime \prime}(\delta(u))\right]\right| \\
& \leq \frac{\left\|h^{\prime}\right\|_{\infty}}{\sqrt{g(\|u\|)}}\left|\langle u, u\rangle-g(\|u\|)+E_{|u|}\left[\left|\operatorname{trace}(D u)^{2}\right|\right]\right|+2 \frac{\left\|h^{\prime}\right\|_{\infty}}{g(\|u\|)} E_{|u|}[|\langle(D u) u, \delta(D u)\rangle|]
\end{aligned}
$$

which yields (3.2) by (2.5) and the conditional Skorohod isometry

$$
\begin{equation*}
\operatorname{Var}_{|u|}[\delta(u)]=E_{|u|}\left[\delta(u)^{2}\right]=\langle u, u\rangle+E_{|u|}\left[\operatorname{trace}(D u)^{2}\right] \tag{3.3}
\end{equation*}
$$

that follows from (2.2) with $f(x)=x$ and $n=1$.
When $\left(u_{t}\right)_{t \in \mathbb{R}_{+}}$is a quasi-nilpotent processes, and in particular when $\left(u_{t}\right)_{t \in \mathbb{R}_{+}}$is $\left(\mathcal{F}_{t}\right)_{t \in \mathbb{R}_{+}}$-adapted process, we obtain the following corollary.

Corollary 3.2 Let $u \in \bigcap_{k=1}^{3} \mathbb{D}_{k, 2}(H)$, such that $\left\langle u,(D u)^{2} u\right\rangle=\langle u,(D u) u\rangle=0$ and $\operatorname{trace}(D u)^{2}=0$. We have

$$
d_{|u|}\left(\delta(u), \mathcal{N}_{g(\|u\|)}\right) \leq \frac{1}{\sqrt{g(\|u\|)}}|\langle u, u\rangle-g(\|u\|)|+\frac{2}{g(\|u\|)} E_{|u|}[|\langle(D u) u, \delta(D u)\rangle|] .
$$

Proof. This follows from Proposition 3.1 and the isometry (3.3).
Note that from Proposition 2.1 we have

$$
d_{|u|}\left(\delta(u), \mathcal{N}_{g(\|u\|)}\right)=|\sqrt{\langle u, u\rangle}-\sqrt{g(\|u\|)}| \leq \frac{1}{\sqrt{g(\|u\|)}}|\langle u, u\rangle-g(\|u\|)|
$$

if, in addition to trace $(D u)^{2}=0$, the condition $\left\langle u,(D u)^{k} u\right\rangle=0$ holds for all $k \geq 1$.

Regarding multiple stochastic integrals, we have the following corollary.
Corollary 3.3 Given $f_{m} \in L^{2}\left(\mathbb{R}_{+}^{m}\right)$ a symmetric function in $m \geq 1$ variables, let $u_{t}:=I_{m-1}\left(f_{m}(*, t)\right), t \in \mathbb{R}_{+}$, and assume that $\left\langle u,(D u)^{2} u\right\rangle=\langle u,(D u) u\rangle=0$. Then we have

$$
\begin{equation*}
d_{|u|}\left(I_{m}\left(f_{m}\right), \mathcal{N}_{g(\|u\|)}\right) \leq \frac{1}{\sqrt{g(\|u\|)}}\left|g(\|u\|)-\operatorname{Var}_{|u|}\left[I_{m}\left(f_{m}\right)\right]\right| \tag{3.4}
\end{equation*}
$$

Proof. We have $\langle(D u) u, \delta(D u)\rangle=(m-1)\langle(D u) u, u\rangle=0$, hence the conclusion follows from Proposition 3.1.

In particular, Corollary 3.3 shows that, given $\|u\|$, the multiple stochastic integral $I_{m}\left(f_{m}\right)$ is Gaussian distributed with mean 0 and variance $g(\|u\|):=\operatorname{Var}_{|u|}\left[I_{m}\left(f_{m}\right)\right]$.

## 4 Double stochastic integrals

In this section we take $\left(u_{t}\right)_{t \in \mathbb{R}_{+}}$of the form $u_{t}=I_{1}\left(f_{2}(*, t)\right), t \in \mathbb{R}_{+}$, where the function $f_{2} \in L^{2}\left(\mathbb{R}_{+}^{2}\right)$ may not be symmetric in its two variables. In this case we have $\delta(u)=I_{2}\left(\tilde{f}_{2}\right)$, where $\tilde{f}_{2}$ is the symmetrization of $f_{2}$, with $D_{s} u_{t}=f_{2}(s, t)$ and $\delta\left(D_{s} u\right)=I_{1}\left(f_{2}(s, *)\right), s, t \in \mathbb{R}_{+}$.

Proposition 4.1 The condition $\langle u,(D u) u\rangle=0$ implies $\left\langle u,(D u)^{2} u\right\rangle=0$ and is equivalent to $(D u)^{2}=0$, i.e. to the vanishing of the contraction

$$
\begin{equation*}
\left(f_{2} \otimes_{1} f_{2}\right)\left(t_{1}, t_{2}\right):=\int_{0}^{\infty} f_{2}\left(t_{1}, s\right) f_{2}\left(s, t_{2}\right) d s=0, \quad t_{1}, t_{2} \in \mathbb{R}_{+} \tag{4.1}
\end{equation*}
$$

and in this case, we have

$$
d_{|u|}\left(I_{2}\left(\tilde{f}_{2}\right), \mathcal{N}_{g(\|u\|)}\right) \leq \frac{1}{\sqrt{g(\|u\|)}}|g(\|u\|)-\langle u, u\rangle| .
$$

In particular, $I_{2}\left(\tilde{f}_{2}\right)$ is Gaussian $\mathcal{N}_{\|u\|^{2}}$-distributed given $\langle u, u\rangle$.
Proof. By Itô calculus we have

$$
\begin{align*}
& \langle u,(D u) u\rangle=\int_{0}^{\infty} \int_{0}^{\infty} I_{1}\left(f_{2}(*, s)\right) f_{2}(s, t) I_{1}\left(f_{2}(*, t)\right) d s d t  \tag{4.2}\\
& =\int_{0}^{\infty} \int_{0}^{\infty} \int_{0}^{\infty} f_{2}(r, s) f_{2}(s, t) f_{2}(r, t) d r d s d t+\int_{0}^{\infty} \int_{0}^{\infty} f_{2}(s, t) I_{2}\left(f_{2}(*, s) \otimes f_{2}(*, t)\right) d s d t
\end{align*}
$$

hence the condition $\langle u,(D u) u\rangle=0$ is equivalent to the vanishing

$$
\begin{equation*}
\int_{0}^{\infty} \int_{0}^{\infty} f_{2}\left(t_{1}, s\right) f_{2}(s, t) f_{2}\left(t_{2}, t\right) d s d t=0, \quad t_{1}, t_{2} \in \mathbb{R}_{+}, \tag{4.3}
\end{equation*}
$$

i.e.

$$
\int_{0}^{\infty} \int_{0}^{\infty} \int_{0}^{\infty} \int_{0}^{\infty} h\left(t_{1}\right) f_{2}\left(t_{1}, s\right) f_{2}(s, t) f_{2}\left(t_{2}, t\right) g\left(t_{2}\right) d s d t d t_{1} d t_{2}=0
$$

and taking

$$
g\left(t_{2}\right):=\int_{0}^{\infty} f_{2}\left(r, t_{2}\right) h(r) d r,
$$

we get

$$
\int_{0}^{\infty} \int_{0}^{\infty} \int_{0}^{\infty}\left(\int_{0}^{\infty} f_{2}\left(t_{1}, s\right) f_{2}(s, t) h\left(t_{1}\right) d t_{1}\right)\left(\int_{0}^{\infty} f_{2}\left(r, t_{2}\right) f_{2}\left(t_{2}, t\right) h(r) d r\right) d s d t d t_{2}
$$

$$
=\int_{0}^{\infty}\left(\int_{0}^{\infty} \int_{0}^{\infty} f_{2}(r, s) f_{2}(s, t) h(r) d r d s\right)^{2} d t=0
$$

hence the condition

$$
\int_{0}^{\infty} f_{2}(r, s) f_{2}(s, t) d s=0, \quad r, t \in \mathbb{R}_{+}
$$

which becomes equivalent to (4.3). Consequently we have trace $\left(f_{2}\right)^{2}=0$, hence by (3.3) we get $\operatorname{Var}_{|u|}\left[I_{2}\left(\tilde{f}_{2}\right)\right]=\langle u, u\rangle$. Moreover, we note that

$$
\begin{aligned}
\langle(D u) u, \delta(D u)\rangle= & \int_{0}^{\infty} \int_{0}^{\infty} u_{s} D_{s} u_{t} \delta\left(D_{t} u\right) d s d t \\
= & \int_{0}^{\infty} \int_{0}^{\infty} I_{1}\left(f_{2}(*, s)\right) f_{2}(s, t) I_{1}\left(f_{2}(t, *)\right) d s d t \\
= & \int_{0}^{\infty} \int_{0}^{\infty} \int_{0}^{\infty} f_{2}(r, s) f_{2}(s, t) f_{2}(t, r) d r d s d t \\
& +\frac{1}{2} I_{2}\left(\int_{0}^{\infty} \int_{0}^{\infty} f_{2}(s, t)\left(f_{2}(*, s) f_{2}(t, \cdot)+f_{2}(\cdot, s) f_{2}(t, *)\right) d s d t\right) \\
= & 0,
\end{aligned}
$$

and we conclude by Proposition 3.1.
Examples of functions satisfying (4.1) can be given by choosing $\left(e_{k}\right)_{k \geq 1}$ an orthonormal system in $L^{2}([0, T])$ and letting

$$
f_{2}(s, t):=\sum_{i, j=1}^{d} a_{i, j} e_{i}(s) e_{j}(t), \quad s, t \in[0, T],
$$

where $A=\left(a_{i, j}\right)_{1 \leq i, j \leq d}$ is a 2-nilpotent $d \times d$ matrix. Note that the vanishing (4.1) of the contraction $f_{2} \otimes_{2} f_{2}$ implies $f_{2}=0$ if the function $f_{2}$ is symmetric in its two variables, similarly we have $A=0$ if $A$ is symmetric and 2-nilpotent.

Next, given $A=\left(a_{i, j}\right)_{1 \leq i, j \leq d}$ an $d \times d$ matrix, we note that the quadratic functional $\int_{0}^{T} A W_{s} d W_{s}$ of the $n$-dimensional Brownian motion

$$
W_{t}:=\left(B_{t}, B_{T+t}-B_{T}, \ldots, B_{(n-1) T+t}-B_{(n-1) T}\right), \quad t \in[0, T],
$$

can be represented as

$$
\begin{equation*}
I_{2}\left(\tilde{f}_{2}\right)=\int_{0}^{T} A W_{s} d W_{s} \tag{4.4}
\end{equation*}
$$

where $f_{2}$ is the function

$$
f_{2}(s, t):=\sum_{i, j=1}^{d} a_{i, j} \mathbf{1}_{[(j-1) T,(j-1) T+t-(i-1) T]}(s) \mathbf{1}_{[(i-1) T, i T]}(t), \quad s, t \in[0, n T],
$$

as we have

$$
\begin{aligned}
I_{2}\left(\tilde{f}_{2}\right)= & \sum_{i, j=1}^{d} a_{i, j} \int_{0}^{T} \int_{0}^{t+(i-1) T} \mathbf{1}_{[(j-1) T,(j-i) T+t+(i-1) T]}(s) d B_{s} d W_{t}^{i} \\
& +\sum_{i, j=1}^{d} a_{i, j} \int_{(j-1) T}^{n T} \int_{(i-1) T}^{t \wedge(i T)} \mathbf{1}_{[(j-1) T,(j-i) T+s]}(t) d B_{s} d B_{t} \\
= & \sum_{1 \leq j \leq i \leq n} a_{i, j} \int_{0}^{T} \int_{(j-1) T}^{t+(j-1) T} d B_{s} d W_{t}^{i}+\sum_{1 \leq i<j \leq n} a_{i, j} \int_{(j-1) T}^{j T} \int_{(i-1) T}^{t} d B_{s} d B_{t} \\
= & \sum_{1 \leq j \leq i \leq n} a_{i, j} \int_{0}^{T} \int_{0}^{t} d W_{s}^{j} d W_{t}^{i}+\sum_{1 \leq i<j \leq n} a_{i, j} \int_{0}^{T} \int_{0}^{t} d W_{s}^{j} d W_{t}^{i} \\
= & \int_{0}^{T} A W_{s} d W_{s},
\end{aligned}
$$

with

$$
\begin{aligned}
\int_{0}^{n T}\left(I_{1}\left(f_{2}(*, t)\right)^{2} d t\right. & =\sum_{i=1}^{d} \int_{(i-1) T}^{i T}\left(\sum_{j=1}^{d} a_{i, j}\left(B_{(j-1) T+t-(i-1) T}-B_{(j-1) T}\right)\right)^{2} d t \\
& =\int_{0}^{T}\left|A W_{t}\right|^{2} d t
\end{aligned}
$$

Note that here, the process $\left(u_{t}\right)_{t \in[0, T]}=\left(I_{1}\left(f_{2}(*, t)\right)\right)_{t \in[0, T]}$ is not $\left(\mathcal{F}_{t}\right)_{t \in[0, T]}$-adapted. As a consequence of Proposition 4.1 we have the following.

Corollary 4.2 The condition $\langle u,(D u) u\rangle=0$ is satisfied if and only if the $d \times d$ matrix A is 2-nilpotent, and in this case we have

$$
\left.d_{|u|}\left(\int_{0}^{T} A W_{s} d W_{s}, \mathcal{N}_{g(\|u\|)}\right) \leq\left.\frac{1}{\sqrt{g(\|u\|)}}\left|g(\|u\|)-\int_{0}^{T}\right| A W_{t}\right|^{2} d t \right\rvert\, .
$$

Proof. We have

$$
\begin{aligned}
& \int_{0}^{n T} \int_{0}^{n T} f_{2}\left(t_{1}, s\right) f_{2}(s, t) f_{2}\left(t_{2}, t\right) d s d t \\
& =\sum_{i, j=1}^{d} \sum_{k, l=1}^{d} \sum_{p, q=1}^{d} \int_{0}^{n T} \int_{0}^{n T} \mathbf{1}_{[(j-1) T,(j-1) T+t-(i-1) T]}\left(t_{2}\right) \mathbf{1}_{[(q-1) T,(q-1) T+s-(p-1) T]}\left(t_{1}\right) a_{i, j} a_{k, l} a_{p, q}
\end{aligned}
$$

$$
\begin{aligned}
& \mathbf{1}_{[(i-1) T, i T]}(t) \mathbf{1}_{[(k-1) T, k T]}(t) \mathbf{1}_{[(l-1) T,(l-1) T+t-(i-1) T]}(s) \mathbf{1}_{[(p-1) T, p T]}(s) d s d t \\
&= \sum_{i, j=1}^{d} \sum_{l=1}^{d} \sum_{q=1}^{d} \int_{(l-1) T}^{l T} \int_{(i-1) T}^{i T} \mathbf{1}_{[(j-1) T,(j-1) T+t-(i-1) T]}\left(t_{2}\right) \mathbf{1}_{[(q-1) T,(q-1) T+s-(p-1) T]}\left(t_{1}\right) a_{i, j} a_{i, l} a_{l, q} \\
& \mathbf{1}_{[(l-1) T,(l-1) T+t-(i-1) T]}(s) d s d t \\
&= \sum_{j, q=1}^{d} \int_{0}^{T} \int_{0}^{T} \mathbf{1}_{[(j-1) T,(j-1) T+t]}\left(t_{2}\right) \mathbf{1}_{[(q-1) T,(q-1) T+s]}\left(t_{1}\right) \mathbf{1}_{[0, t]}(s) d s d t \sum_{i, l=1}^{d} a_{i, j} a_{i, l} a_{l, q} \\
&= \sum_{j, q=1}^{d}\left(A^{\top} A^{2}\right)_{j, q} \int_{0}^{T} \int_{0}^{T} \mathbf{1}_{[(j-1) T,(j-1) T+t]}\left(t_{2}\right) \mathbf{1}_{[(q-1) T,(q-1) T+s]}\left(t_{1}\right) \mathbf{1}_{[0, t]}(s) d s d t,
\end{aligned}
$$

$t_{1}, t_{2} \in[0, T]$, hence from (4.2), $\langle u,(D u) u\rangle=0$ implies $A^{\top} A^{2}=0$, which in turn implies $A^{2}=0$ by the relation $\left\langle A^{2} x, A^{2} x\right\rangle_{\mathbb{R}^{d}}=\left\langle A x, A^{\top} A^{2} x\right\rangle_{\mathbb{R}^{d}}, x \in \mathbb{R}^{d}$.
In particular, taking $g(x)=x^{2}$, Corollary 4.2 shows that, given $\int_{0}^{T}\left|A W_{t}\right|^{2} d t$, the quadratic functional $\int_{0}^{T} A W_{t} d W_{t}$ is Gaussian with variance $\int_{0}^{T}\left|A W_{t}\right|^{2} d t$ when $A^{2}=0$, which recovers Corollary 3 in [12] under the condition of [13].

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